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#### S-38.3180: Quality of Service in Internet

Lecture I: Egress Traffic Processing

9.11.2006



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# **Egress Processing**

- Scheduling
  - Decission of ordering of packets
    - Which packet is going to be sent out to the link next
  - Control of network link resource
    - Differentiation of 1<sup>st</sup> parameter (throughput)
    - Partial control over 2<sup>nd</sup> parameter (delay)

- Queue Management
  - Decission of when packet should be dropped from the queue and which packet it is going to be
  - Control of buffer resource
    - Differentiation of 3<sup>rd</sup> parameter (loss)
    - Partial control over 2<sup>nd</sup> parameter (delay)

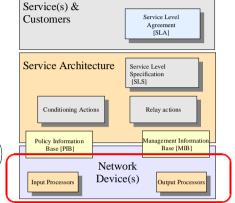


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## Today's Topic

 This lecture is about functional mechanisms which can be found from the output processors of network devices







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#### Queues

- Queues are used to store **contending** packets
  - Contention is temporary event rising from statistical multiplexing
    - Packets from different input links of a router attempt to the same output link at certain time
    - Packets from a higher speed link arrive temporarily too fast for a slower speed link
- If contention is permanent queues overflow i.e. network gets congested
- Difference:
  - Contention packets are not lost only delayed
  - Congestion packets are not only delayed but also lost



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#### Queues

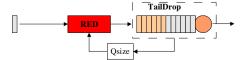
- Congestion situations demand queue management to decide
  - When packets should be discarded
  - Which are the packets that should be discarded
- Prevalent solutions
  - Tail Drop
  - Random Early Detection (RED)
  - Random Early Detection In/Out (RIO)
  - Weighted Random Early Detection (WRED)



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## Random Early Detection

- RED is an active queue management algorithm (AQM), which aims to
  - Prevent global syncronisation
  - Offer better fairness among competing connections
  - Allow transient burst without packet loss
- Algorithm operates on the knowledge of current Qsize and average Qsize (avg)
  - Avg is updated on every arrival and departure from the actual queue





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## Tail Drop

- Simple algorithm:
  - If arriving packets sees a full queue it is discarded
  - Otherwise it is accepted to the end of queue
- Problem:
  - Poor fairness in distribution of buffer space
  - Unable to accommodate short transients when queue is almost full
    - Bursty discarding process leading to global syncronisation
- Global syncronisation is a process where large number of TCP connections syncronise their window control due to concurrent packet losses.
  - Packet losses tend to be bursty, therefore window decreases to one and halts the communication



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#### **RED**

• Qsize is used to calculate average length of the queue:

```
Initial condition: avg(0) = 0
Count = -1
When Qsize = 0: T_{idle} = T_{now}
After every packet arrival: if Qsize (n) > 0: avg(n+1) = (1-\epsilon) \cdot avg(n) + \epsilon \cdot Qsize(n)
else: avg(n+1) = avg(n) \cdot (1-\epsilon)^{f(T_{noc} - T_{obs})}
```

If queue is empty, averaging is done based on the assumption that N packets have passed the algorithm before actual packet arrival. -> Decay of average during idle times

Packets are discarded based on the average queue length:

average queue length: if 
$$avg(n+1) < min_{th}$$
:

$$Count = -1$$
else if  $min_{th} \le avg(n+1) < max_{th}$ 

$$count = count + 1$$

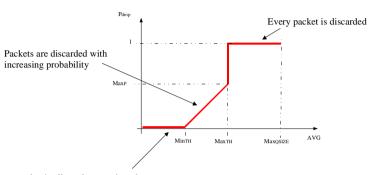
$$P_b(n+1) = max_p \frac{avg(n+1) - min_{th}}{max_{th} - min_{th}}$$

$$P_a(n+1) = \frac{P_b(n+1)}{1 - count \cdot P_b(n+1)}$$
With probability  $P_a(n+1)$ :
Discard packet
$$Count = 0$$
else if  $max_{th} \le avg(n+1)$ 
Discard packet
$$Count = 0$$



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#### **RED**



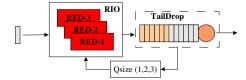
Every packet is allowed to pass into the queue



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#### RED In/Out - WRED

- When we aim for differentiation of resources we must also allow different shares of resources in contending link or buffer
- One way to do it is to use RED with several parallel algorithms and thresholds
  - RED In/Out -> RIO or WRED
  - Popular implementations use two or three parallel algorithms
- · This requires that packets are marked
  - One algorithm is responsible of one or several marks





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#### Achievements of RED

- Some packets are discarded even before overflow of the actual buffer
  - Is it good or bad?
    - Bad: A part of buffer space is in some occasions wasted
    - Good: A signal is sent to cooperating sources that they should decrease their sending rate or congestion will occure
- On the average early packet discards will hit connections which use more than their fair share of capacity in contending link
  - Is it good or bad?
    - Bad: Makes differentiation impossible
    - Good: Is consistent policy and withing the goal of conventional Best Effort model



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#### **RIO**

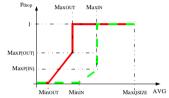
- Operation is usually based on following idea:
  - Customer has contracted capacity of X bps
  - He sends packets with rate Y bps
  - If Y is greater than X, some packets are marked as out of profile.
    - Out of profile packets usually experience harsh treatment on contending situations
- Calculation of the average queue length is modified to take into accout number of packets with different markings:
  - In (green): Only green packets
  - In/Out (yellow): Green and yellow packets
  - Out (red): All packets in the queue

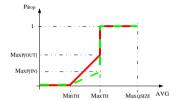


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#### Parameters in WRED

- All parameres are independent for different markings
  - More dimensions in creating differentiation
- Some parameters are common for different markings
  - Less dimensions but more understandable







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# Scheduling

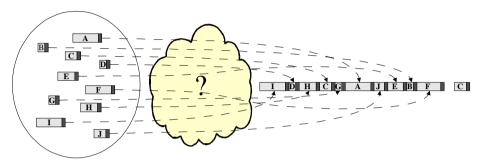
- Selecting the order of packets means that resource sharing is controlled with predefined policy.
- Policy defines the amount of resources which are allocated to the connections / classes / aggregates for which single packets belong to.
- One end in this continum is that predefined amount of resources are allocated to the connections.
- Other end is that no allocation is done and resources are shared on the basis of the need



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## Scheduling

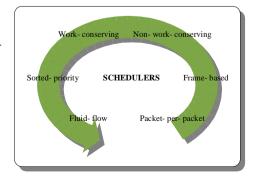
 Task of a scheduler is to decide the order of packets which are transmitted from the queue(s)





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- There are vast amount of schedulers developed for different purposes
- Generally they can be divided into categories of
  - Work-conserving vs non-workconserving
  - Time-based vs frame-based
  - Continuous vs packetized
  - Priority vs no priority





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## Scheduling

- Conservation of work means that scheduler is executing its task as long as it has some work to do.
- Technically this means that there are packets in the queue which has to be sent into the link before scheduler can take a break i.e. change to the idle state.
- Non-work conserving scheduler can idle even though it has packets in the queue.

- Why we would want to have nonwork conserving scheduler?
- Conservation of work means that packets are sent to the link even though receiver would prefer them to come a little bit later.
- This can happen with real-time applications which send packets with constant time intervals. However, network can multiplex them so that they form bursts. Non-work conserving scheduler may delay packets so that intervals structure is maintained throughout the network.



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## Scheduling

#### Time based scheduling

- Uses either arrival time, finishing time or both as a criteria for ordering
- Time may be virtual or real-time depending on scheduler time
- Virtual time is usually finishing time in ideal scheduler i.e. scheduler which is not packetized

#### Frame based scheduling

- Uses fixed frame which is partitioned for the scheduled packets based on their weights.
- During a rotation,
  - If there are enough tokens (partition + left overs), then packet is served.
  - Otherwise tokens are added for the next round.
- A number of packets may be served from a single class if frame is big.

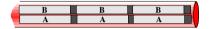


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## Scheduling

#### Continuous time

- Scheduling decissions and calculations are done based on continuous time units
- Fluid-Flow modeling packets are infinitesimally small
- Assumes that number of packets could be served on same time (not possible)



#### Packetized

- Scheduling decissions and calculations are based on packet per packet analysis
- Distorts fluid flow model





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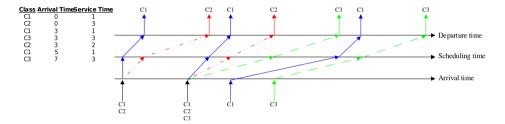
- Scheduling can happen:
  - Within one queue, sorting packets inside queue to appropriate transmission order
  - Between several queues, dispatching head of line packets from different queues
  - Hierarchically over several schedulers, combination of previous ones
- Many of scheduling algorithms can be used to produce QoS in each of these cases



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## Scheduling

- First Come First Served (FCFS) is prevalent scheduling method in routers.
- FCFS uses arrival time information as sorting criteria for packet dispatching.
- FCFS is not able to offer any QoS as arrival time is the only parameter that has influence to the order of packets.

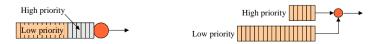




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# Scheduling

- Prioritized ordering may lead to starvation of resources in low priority classes if traffic in high priority classes is not limited.
- This can be accomplished by using
  - Connection admission control
  - Over provisioning
  - Rate control
  - Modifying priority scheduler to take class rates into account (token based operation)

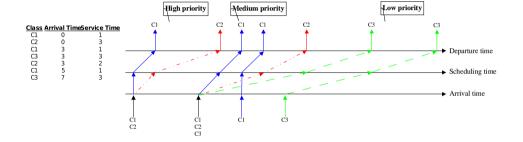




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## Scheduling

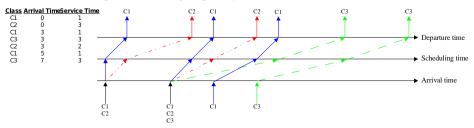
- Simple priority scheduler extends FCFS to be able to distinguish between more and less important traffic.
- Packets are ordered first based on their priority and second on their arrival time.





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- Deadline based scheduling schemes (e.q. Earlies Due Date) are based on the
  calculation of finishing time (i.e. time when a packet would have been
  transmitted if it arrived to empty system).
- Packets are transmitted on the order of finishing times.
  - Small packets have higher priority is this fair ?





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## Scheduling

- <u>Delay based</u> scheduling schemes (e.q. PDD, WPT, HPD) are based on the calculation of queueing delay
  - Long term
  - Short term
  - Combination of both
- Packets are transmitted on the order of
  - Absolute queueing delay
  - Relative queueing delay
    - · Queueing delays are normalized with differentiation factor



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## Scheduling

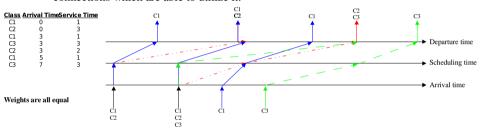
- Disadvantages of GPS are:
  - Departures from GPS are colliding which makes the use of GPS based scheduler impossible
    - However it may be used as background scheduler if collisions are resolved in some manner
  - Heavy calculation of departure times
    - Departure time of every packet in scheduler changes whenever a packet arrives or departs the scheduler



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## Scheduling

- Generalized Processor Sharing is ideal fair queueing algorithm which is based on fluid flow model.
- GPS provides service to the individual connections based on their weights.
- GPS is work conserving scheduler and thus distributes excess capacity to connections which are able to utilize it.





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# Scheduling

- Advantages of GPS are:
  - Fairness which it provides for the sharing connections

$$\frac{\left[Service\left(t,\ t+\Delta t\right)\right]_{i}}{\left[Service\left(t,\ t+\Delta t\right)\right]_{i}} \ge \frac{Weight_{i}}{Weight_{i}}$$

 Strict delay bound caused by scheduling when traffic is constrained by a token bucket of token rate r and bucket depth b

Service rate for connection 
$$i: r_i \ge \frac{Weight_i}{\sum_j Weighth_j} \cdot Link \ Rate$$

$$Delay \ for \ connection \ i: \ D_i \le \frac{b_i}{r_i}$$

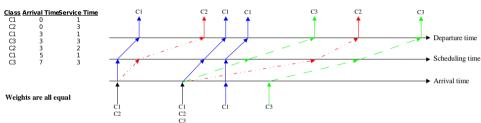
Remember these results were derived from the assumption that packets flow like fluid through the system i.e. there would be a dedicated link with capacity *r* between endpoints.



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## Scheduling

- <u>Packetized Generalized Processor Sharing</u> is packet per packet approximation of GPS scheduling.
- The most prevalent implementation of PGPS is weighted fair queueing (WFQ)
- WFQ uses calculation of finishing time in corresponging GPS system as a criteria for sorting the packets.

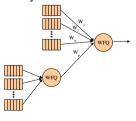




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## Scheduling

- WFQ scheduling has number of variant which aim:
  - Ease the calculation of finishing time in corresponding GPS system
    - By replacing the idle time function with the finishing time of packet which was in service when backlogging packet arrived to the system.
    - By replacing the time calculation with frame based operation
  - Make the fairness packetized system as good as continuous system
  - Allow hierarchical construction of service





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## Scheduling

- Delay bound of WFQ system differs the one of GPS system with two extra components:
  - $\frac{(K-1)L_{max}}{r_i}$

which represents extra delay caused if packet arrives a moment later it would have been served in corresponding GPS system. L is the maximum packet length and K is the number of hops.

 $\sum_{m=1}^{K} \frac{L_{m\alpha}}{R^{m}}$ 

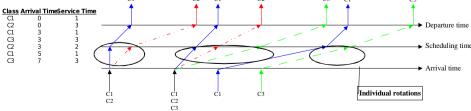
which represents the fact that packets are served one by one. In backlogged system, packet must wait that previous packet is served, before it gets to be scheduled.

$$D_{i} \leq \frac{b_{i}}{r_{i}} + \frac{(K-1)L_{max}}{r_{i}} + \sum_{m=1}^{K} \frac{L_{max}}{R^{m}}$$



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- Weighted Round Robin is popular implementation of frame based fair queueing.
- WRR uses a rotation where each individual connection is served in relation of their weights.
- Service is usually based on packets, which causes WRR to be not able to distribute bandwidth fairly in systems which have variable packet lengths.





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## Scheduling

- **Deficit Round Robin** is extention of WRR which takes account the packet size
- DRR uses a rotation where a frame of *N* bits is divided to indivivual connections in relation to their weights (quantums).
- Quantums which individual connections receive serve packets
  - If the quantum is small, many rotations are required to serve backlogged connection -> approximated WFQ
  - If the quantum is big, many packets can be served on one rotation -> resource usage differs from the policy
- DRR uses special counter for each backlogged connection which stores the information of received bits.
  - If connection gets to non backlogged state counter is cleared



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# Scheduling

- Advantage of CBQ is that scheduling during contention is easily manipulated to produce outcome which is not only based on time and priority information
- Disadvantage is that CBQ requires a lot of processing time when there are a lot
  of independent connections / classes



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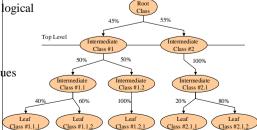
#### Scheduling

- Class Based Queueing is one form hierarchical scheduling
  - In CBO scheduling is divided into two cases:
    - Unregulated: When a class is scheduled by **general scheduler**
    - Regulated: When a class is scheduled by link share scheduler
  - Class is regulated in situations when network is persistently contended and class has run over its limits
- Actual implementation of scheduling is uniform
  - Both schedulers manipulate HOL packets <u>time to send</u> information which is then examined by actual dispatcher.
- · CBQ uses different variants of round robin schedulers as a general scheduler
- Link share scheduler is based on general rules supplied by user



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- Link sharing guidelines are based on tree like structure
  - Link resources are on Root Class
  - Intermediate Classes form logical groupings
    - Organisations
    - Protocols
  - Leaf classes are actual queues with distinct traffic





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# Scheduling

- CBQ has concept of borrowing:
  - If class has run over its limit but it has parent class which is not over its limit, it may borrow capacity from the parent
  - Borrowing may be limited to some level in link sharing tree (<u>Top Level</u>)
- Formal definition between regulated and un regulated follows from borrowing:
  - Class is unregulated if:
    - It is under its limit

or

• It has parent below Top Level which is under its limit



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# **Summary**

- There is a lot of room to make more intelligent and effective scheduling and queue management algorithms
  - Resource adaptation
    - Network status changes -> resource allocation policy changes
    - Delay control for real-time communication
    - P2P
  - Fairness issues
    - How to bring differentiation into the Internet traffic without too much complexity