Size-aware Dispatching Problems in MDP Framework

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6.7.2011, INFORMS APS Size-aware Dispatching Problemsin MDP Framework 1/30

Dispatching Problem to Parallel Queues



- Upon arrival a job is routed to one of the *m* servers
- Each server processes jobs according to a certain scheduling discipline (e.g., FCFS)
- Objective: minimize the mean delay (mean sojourn time)
- Examples: manufacturing sites, job assignment in supercomputing, traffic routing, web-server farms, and other distributed computing systems





Size- and State-aware Dispatching Problem



- Poisson arrival process, rate λ
- m parallel heterogeneous servers
- General job size distribution
- Service requirements become known upon arrival (possibly server specific)
- Queue states (job sizes and their service order) are known
- Scheduling discipline known: FCFS, LCFS, SPT, SRPT
- Dispatching policy α chooses the queue upon arrival
- Objective: minimize the mean delay



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State-independent Policies

1. Bernoulli splitting (RND):

Choose queue in random using probabilities p_i

- 2. Size-Interval-Task-Assignment (SITA): "short jobs to one queue and rest to another"
 - Proposed in Crovella et. al (Sigmetrics'98) and Harchol-Balter et. al (J. of PDC, vol. 59, 1999).
 - SITA-E uses such intervals that balance the load.
 - Optimal size-aware state-free for FCFS (Feng et. al, 2005).



State-dependent Policies

1. Join-the-Shortest-Queue (JSQ):

Optimal when Poisson arrivals, Exp-distributed job sizes, identical servers, and only the queue occupancy is known (Winston, 1977).

2. Round-robin (RR):

Optimal with identical servers that were initially in a same state (Ephremides et. al, 1980).

3. Least-Work-Left (LWL):

Pick the queue with the shortest backlog (Sharifnia, 1997).



Approach: MDP and FPI

- Size- and state-aware setting; future arrivals not known
- Idea: start with a reasonable basic dispatching policy, and carry out the first policy iteration (FPI) step
- Policy iteration finds the optimal policy, and the FPI step typically yields the highest improvement.
- Requires the relative values of states vz
- However, our state-space is quite complex (job sizes etc.)



Delay Costs and Relative Value

Delay costs are accrued at rate

 $N_{z}(t) \triangleq$ "the number of jobs in the system",

where **z** denotes the initial state at time t = 0.

The delay costs accrued during (0, t) are

$$V_{\mathbf{z}}(t) \triangleq \int_0^t N_{\mathbf{z}}(s) \, ds.$$

The relative value is the expected difference in the cumulative costs between a system initially in state z and a system initially in equilibrium,

$$\nu_{\mathbf{z}} \triangleq \lim_{t \to \infty} \mathbb{E}[V_{\mathbf{z}} - r t]$$
$$= \lim_{t \to \infty} \left(\mathbb{E}\left[\int_0^t N_{\mathbf{z}}(s) \, ds\right] - \mathbb{E}[N] t \right).$$



First Policy Iteration (FPI)

- Assume: Relative values v_z available (for basic policy)
- Improved decision according to FPI at state z:

$$\alpha(\mathbf{z}, \mathbf{x}) \triangleq \underset{i}{\operatorname{argmin}} \left(\mathbf{v}_{\mathbf{z}'(i)} - \mathbf{v}_{\mathbf{z}} \right),$$

where $\mathbf{z}'(i)$ is the new state if job *x* is added to queue *i*.

"choose the action with the smallest expected future cost"

- Recall: in addition to z, relative value vz depends also on
 - 1. basic dispatching policy
 - 2. scheduling discipline
 - 3. arrival rate λ , and
 - 4. job size distribution.



Decomposition to Independent M/G/1 Queues

- Deriving relative values is generally difficult task.
- However, any state-independent policy feeds each server jobs according to a Poisson process (cf. Bernoulli split)



Analyze single M/G/1 queues instead?



Relative Values for Single M/G/1 Queue

Plan:

- Assume a state-independent basic policy.
- Derive relative values for the "isolated queues" first.
- Relative value of the whole system for any state-independent policy is the sum of the queue specific relative values:

$$V_{\mathbf{Z}} = \sum_{i} V_{\mathbf{Z}_{i}}.$$

• Carry out the FPI step \Rightarrow new efficient policy. (In practice, it is sufficient to know, e.g., $v_z - v_0$.)

Next step:

Derive $v_z - v_0$ for an M/G/1 queue with LCFS, FCFS, SPT and SRPT.





M/G/1-LCFS (preemptive)

Notation:

- λ is the Poisson arrival rate.
- $\rho = \lambda E[X]$ and E[X] denotes the mean job size.
- Z = (Δ₁; ..; Δ_n) denotes the state, where Δ_i is the known (remaining) service time of job i, i = 1, .., n.
- ► The *n*th job is the latest arrival currently being processed.

Proposition: The size-aware relative value of state **z** with respect to delay in an M/G/1-LCFS queue is

$$v_{(\Delta_1;\ldots;\Delta_n)} - v_0 = \frac{1}{1-\rho}\sum_{i=1}^n i\cdot\Delta_i.$$

Insensitivity: $v_{(\Delta_1;..;\Delta_n)} - v_0$ depends only on ρ .



Proof

- Consider two systems under same arrivals:
 - 1. S1 initially in state $\mathbf{z} = (\Delta_1, .., \Delta_n)$,
 - 2. S2 initially empty.
- Let D_i denote the (remaining) delay of job *i* in S1.
- With LCFS, the current state has no effect on the future arrivals' sojourn times.
- The difference between the relative value of S1 and S2 is equal to the mean remaining delay of the *n* present jobs,

$$v_{(\Delta_1;\ldots;\Delta_n)} - v_0 = \sum_{i=1}^n \mathrm{E}[D_i].$$





• Remaining delay D_n of job *n* is given by a random sum,

$$D_n = \Delta_n + (B_1 + \ldots + B_{A(\Delta_n)})$$

where $A(\Delta_n)$ denotes the number of (mini) busy periods during time Δ_n , and B_i the corresponding durations,

$$\mathbf{E}[B_i] = \mathbf{E}[X]/(1-\rho).$$

Taking the expectation on both sides gives

$$E[D_n] = \Delta_n + E[A(\Delta_n)] \cdot E[B] = \frac{\Delta_n}{1 - \rho}$$

Similarly, $E[D_i] = (1 - \rho)^{-1} \sum_{j=i}^n \Delta_j$.
$$\Rightarrow \quad \mathbf{v_z} - \mathbf{v_0} = \sum_{i=1}^n E[D_i] = \boxed{\frac{1}{1 - \rho} \sum_{i=1}^n i \cdot \Delta_i}.$$



M/G/1-FCFS Notation:

- λ is the Poisson arrival rate.
- $\rho = \lambda E[X]$ and E[X] denotes the mean job size.
- Let z = (Δ₁; ..; Δ_n) denote the state, where Δ_i is the known (remaining) service time of job i, i = 1, .., n.
- The nth job is served first.

Proposition: The size-aware relative value of state **z** with respect to the delay in an M/G/1-FCFS queue is given by

$$v_{(\Delta_1;\ldots;\Delta_n)} - v_0 = \frac{\lambda u_z^2}{2(1-\rho)} + \sum_{i=1}^n i \Delta_i,$$

where $u_{\mathbf{z}} = \sum_{i} \Delta_{i}$ denotes the backlog in the queue. Insensitivity: $v_{(\Delta_{1};..;\Delta_{n})} - v_{0}$ depends only on λ and $\mathbb{E}[X]$.



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Proof

Consider two systems under the same arrivals:

- S1 initially in state $\mathbf{z} = (\Delta_1; ..; \Delta_n)$ and
- S2 initially empty.

Both systems behave identically once S1 becomes empty. The difference in the relative values is equal to the additional time jobs spent in S1,

$$v_{\mathbf{z}}-v_0=V_1+V_2,$$

where V_1 denotes the (remaining) delay of present jobs, and V_2 the additional mean delay the later arrivals experience in S1.

The total delay of the *n* present jobs in S1 is already fixed,

$$V_1 = \sum_{i=1}^n i \,\Delta_i.$$



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A later arriving task starts a busy period in S2, which corresponds to a mini busy period in S1.



- During busy periods, arriving jobs increase the cumulative delay by an amount equal to the post arrival workload.
- These jobs experience an additional delay Y in S1.
- Otherwise the delay contributions are equal!



Summing up:

- Mean number of busy periods before S1 empty: \u03c4 uz.
- Mean number of jobs served during a busy period: $1/(1 \rho)$.
- The mean offset $E[Y] = u_z/2$.

Therefore,

$$V_2 = \lambda \, u_{\mathbf{z}} \cdot \frac{1}{1-\rho} \cdot \frac{u_{\mathbf{z}}}{2}$$
$$= \frac{\lambda \, u_{\mathbf{z}}^2}{2(1-\rho)},$$

Initial state z:

Initially empty system:



and $V_1 + V_2 = v_z - v_0$, which completes the proof.



M/G/1-SPT (Non-preemptive)

Notation

- Z = (Δ₁; ..; Δ_n) denotes the state of a queue; job *n* is currently receiving service, jobs 1, ..., (n − 1) wait in the queue, so that Δ₁ > Δ₂ > ... > Δ_{n−1}. (SPT order)
- Let f(x) denote the job size pdf.
- $\rho(x) = \lambda \int_0^x x f(x) dx$, i.e., load due to jobs shorter than x.
- Define $\tilde{\Delta}_0 = \infty$, $\tilde{\Delta}_n = 0$ and $\tilde{\Delta}_i = \Delta_i$ for $i = 1, \dots, (n-1)$.

$$\begin{split} \mathbf{v}_{(\Delta_1;..;\Delta_n)} &- \mathbf{v}_0 = \sum_{i=1}^n \left(\Delta_i + \frac{\sum_{j=i+1}^n \Delta_j}{1 - \rho(\Delta_i)} \right) + \\ \frac{\lambda}{2} \sum_{i=1}^n \left(\left(\sum_{j=1}^{i-1} \Delta_j^2 + \left(\sum_{j=i}^n \Delta_j \right)^2 \right) \int_{\tilde{\Delta}_i}^{\tilde{\Delta}_{i-1}} \frac{f(x)}{(1 - \rho(x))^2} \, dx \right). \end{split}$$

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M/G/1-SRPT

The size-aware relative value of state \mathbf{z} with respect to delay in an M/G/1-SRPT queue is

$$\begin{aligned} \mathbf{v}_{\mathbf{z}} - \mathbf{v}_{0} &= \sum_{i=1}^{n} \left(\Delta_{i} + \frac{u_{\mathbf{z}}(\Delta_{i})}{1 - \rho(\Delta_{i})} + \int_{0}^{\Delta_{i}} \frac{\rho(t)}{1 - \rho(t)} dt \right) \\ &+ \int_{0}^{\infty} \frac{\lambda f(x) \left(u_{\mathbf{z}}(x)^{2} + n_{\mathbf{z}}(x) x^{2} \right)}{2(1 - \rho(x))^{2}} dx, \end{aligned}$$

where

- f(x) = job size pdf,
- $\rho(x)$ = offered load due to jobs shorter than x,
- $u_z(x)$ = backlog due to jobs shorter than x in state z,
- n_z(x) = number of jobs longer than x in state z.



SITA with Switch

First application of the relative values:

- Consider a SITA policy with identical servers
- The role of any two servers can be exchanged, e.g., after a state change (arrival)
- Relative values tell us when this is beneficial

Example:

Two identical FCFS queues and SITA-E (equal load per queue)

Switch: short jobs to queue with smaller backlog.

 \Rightarrow New policy: SITA-E with Switch (SITA-Es)

(Generalizes to n > 2 queues)



Numerical Examples

Example 1

- Two identical queues with FCFS
- Job size distribution:
 - 1. Uniform U(0,2)
 - 2. Exponential Exp(1) 3. Pareto(β) with β = 3:

$$P\{X > t\} = (1 + t)^{-\beta}$$

- Performance metrics:
 - 1. Absolute mean delay (sojourn time)
 - 2. Relative delay when compared to SITA-E policy

Example 2

- Two identical queues with SRPT
- Exponential job size distribution, Exp(1)
- Relative delay when compared to a single shared SRPT queue processed by two identical servers



21/30

FCFS and Uniformly distributed jobs



Figure: Mean delay under FCFS with uniformly distributed job sizes.





FCFS and Uniformly distributed jobs



FCFS and Exponentially distributed jobs



Figure: Mean delay under FCFS with Exp-distributed job sizes.



FCFS and Exponentially distributed jobs





FCFS and Pareto distributed jobs



Figure: Mean delay under FCFS with Pareto distributed job sizes.



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FCFS and Pareto distributed jobs



SRPT and Exponentially distributed jobs



- Dispatching system vs. a shared queue with SRPT.
- Appears that the disadvantage due to the dispatching can be insignificant (here order of 5% with FPI-RND).



Conclusions

- Size- and state-aware dispatching problem can be approached in MDP framework
- Corresponding relative values required for the FPI step.
- For state-independent basic policies, sufficient to analyze M/G/1 queue in isolation
- Size-aware relative values for FCFS, LCFS, SPT and SRPT with respect to delay are available for M/G/1
- For FCFS and LCFS, the relative values are insensitive to job size distribution
- ► For SPT and SRPT, the relatives values in integral form.
- Robust, efficient and state-dependent dispatching policies taking into account the current and later arriving tasks

Thanks!



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