



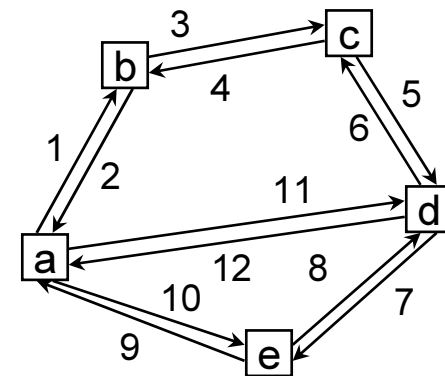
12. Traffic engineering

Contents

- Topology
- Traffic matrix
- Traffic engineering
- Load balancing

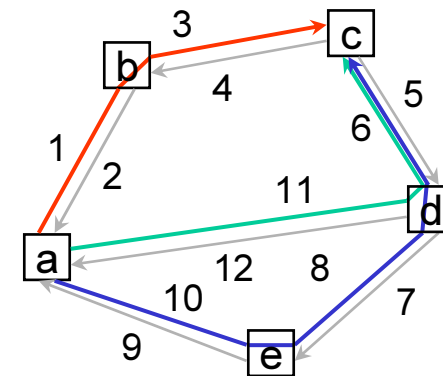
Topology

- A telecommunication network consists of nodes and links
 - Let N denote the set of nodes indexed with n
 - Let J denote the set of nodes indexed with n
- Example:
 - $N = \{a, b, c, d, e\}$
 - $J = \{1, 2, 3, \dots, 12\}$
 - link 1 from node a to node b
 - link 2 from node b to node a
- Let c_j denote the capacity of link j (bps)



Paths

- We define a **path** (= route) as a
 - set of consecutive links connecting two nodes
 - Let P denote the set of paths indexed with p
- Example:
 - three paths from node a to node c:
 - red path consisting of links 1 and 3
 - green path consisting of links 11 and 6
 - blue path consisting of links 10, 8 and 6



Path matrix

- Each path consists of a set of links
- This connection is described by the **path matrix A**, for which
 - element $a_{jp} = 1$ if $j \in p$, that is, link j belongs to path p
 - otherwise $a_{jp} = 0$
- Example:
 - three columns of a path matrix

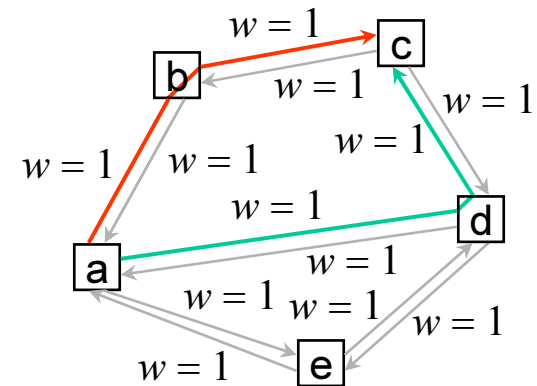
	ac1	ac2	ac3
1	1	0	0
2	0	0	0
3	1	0	0
4	0	0	0
5	0	0	0
6	0	1	1
7	0	0	0
8	0	0	1
9	0	0	0
10	0	0	1
11	0	1	0
12	0	0	0

Shortest paths

- If each link j is associated with a corresponding weight w_j , the length l_p of path p is given by

$$l_p = \sum_{j \in p} w_j$$

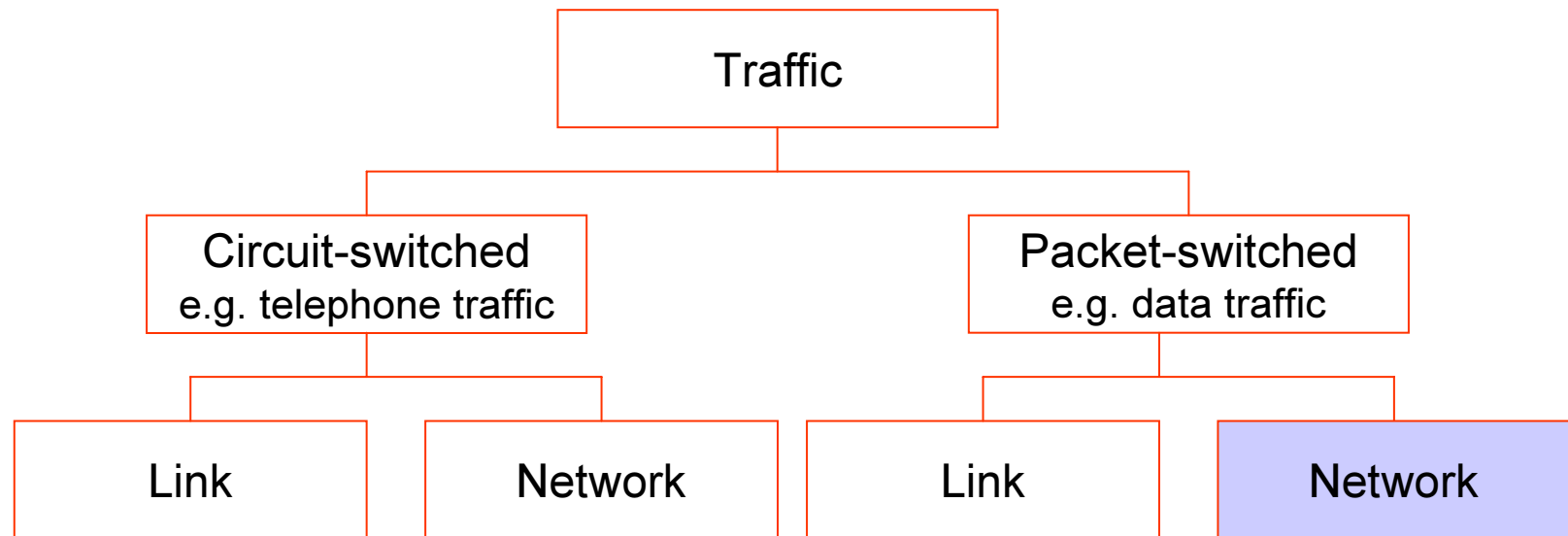
- With unit link weights $w_j = 1$, path length = hop count
- Example:
 - two shortest paths (with length 2) from node a to node c



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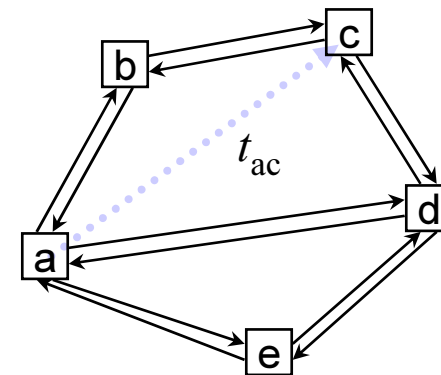
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Traffic characterisation



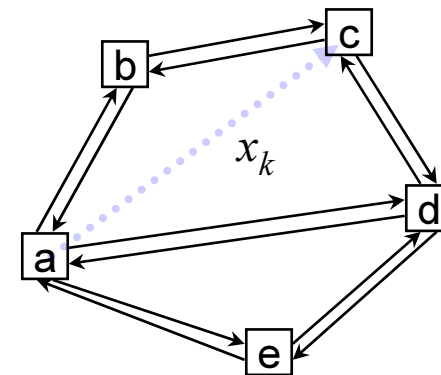
Traffic matrix (1)

- Traffic in a network is described by the **traffic matrix \mathbf{T}** , for which
 - element t_{nm} tells the **traffic demand** (bps) from origin node n to destination node m
 - Aggregated traffic of all flows with the same origin and destination
 - Aggregated traffic during a time interval, e.g. busy hour or "typical 5-minute interval"
- Example:
 - Traffic demand from origin a to destination c is t_{ac} (bps)



Traffic matrix (2)

- Below we present the traffic demands in a vector form
 - Let K denote the set of origin-destination pairs (**OD-pairs**) indexed with k
- Traffic demands constitute a vector \mathbf{x} , for which
 - element x_k tells the traffic demand of OD-pair k
- Example:
 - if OD-pair (a,c) is indexed with k , then $x_k = t_{ac}$



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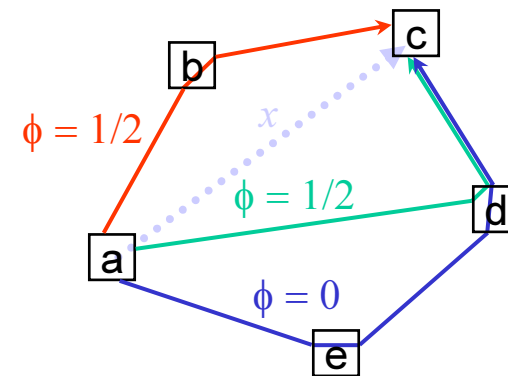
Traffic engineering and network design

- **Traffic engineering** = "Engineer the traffic to fit the topology"
 - Given a fixed topology and a traffic matrix, how to **route** these traffic demands?
- **Network design** = "Engineer the topology to fit the traffic"

Effect of routing on load distribution

- Routing algorithm determines how the traffic load is distributed to the links
 - Internet routing protocols (RIP, OSPF, BGP) apply the shortest path algorithms (Bellman-Ford, Dijkstra)
 - In MPLS networks, other algorithms are also possible
- More precisely: routing algorithm determines the proportions (**splitting ratios**) ϕ_{pk} of traffic demands x_k allocated to paths p ,

$$\sum_{p \in P} \phi_{pk} = 1 \quad \text{for all } k$$



Link counts

- Traffic on a path p between OD-pair k is thus

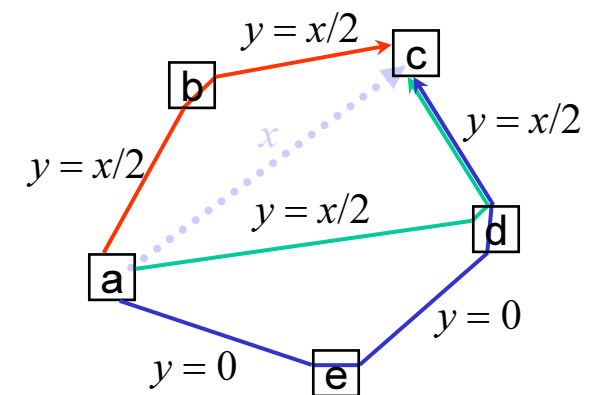
$$\phi_{pk} x_k$$

- Link counts** y_j are determined by traffic demands x_k and splitting ratios ϕ_{pk} :

$$y_j = \sum_{p \in P} \sum_{k \in K} a_{jp} \phi_{pk} x_k$$

- The same in matrix form:

$$\mathbf{y} = \mathbf{A} \phi \mathbf{x}$$



MPLS

- **MPLS** (Multiprotocol Label Switching) supports traffic load distribution to parallel paths between OD-pairs
 - In MPLS networks, there can be any number of parallel Label Switched Paths (LSP) between OD-pairs
 - These paths do not need to belong to the set of shortest paths
 - Each LSP is associated with a label and each MPLS packet is tagged with such a label
- MPLS packets are routed through the network via these LSP's (according to their label)
- Traffic load distribution can be affected **directly** by changing the splitting ratios ϕ_{pk} at the origin nodes

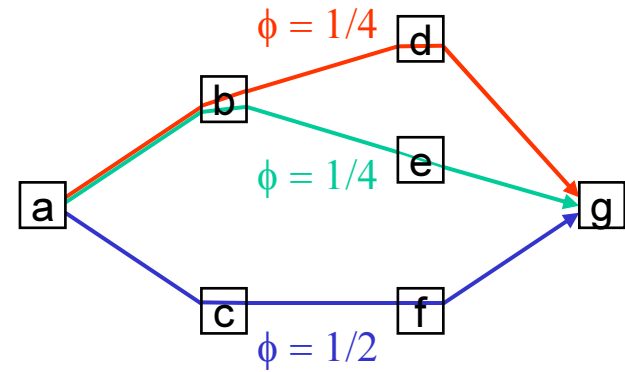
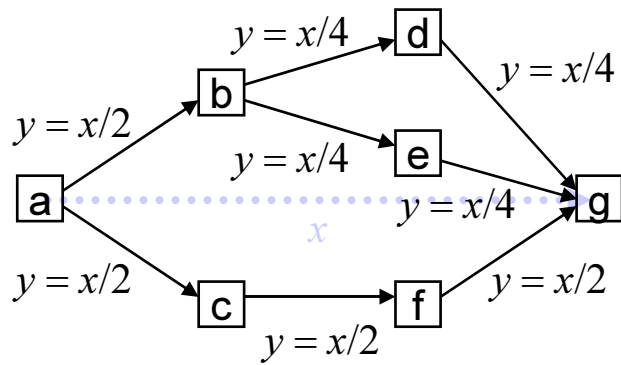
OSPF (1)

- **OSPF** (Open Shortest Path First) is an intradomain routing protocol in IP networks
- Link State Protocol
 - each node tells the other nodes the distance to its neighbouring nodes
 - these distances are the link weights for the shortest path algorithm
 - based on this information, each node is aware of the whole topology of the domain
 - the shortest paths are derived from this topology using Dijkstra's algorithm
- IP packets are routed through the network via these shortest paths

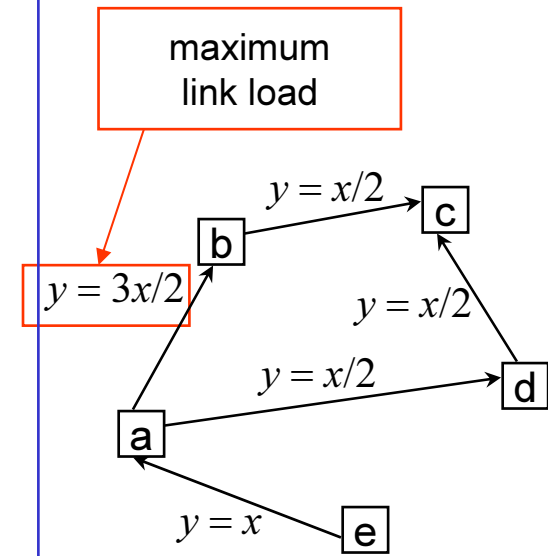
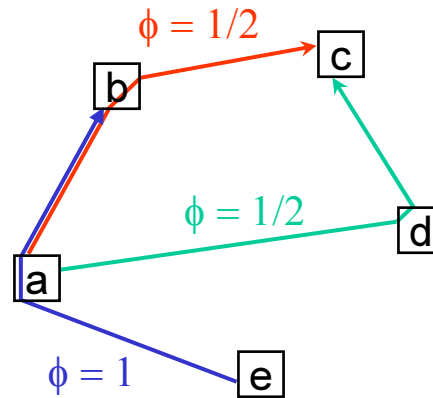
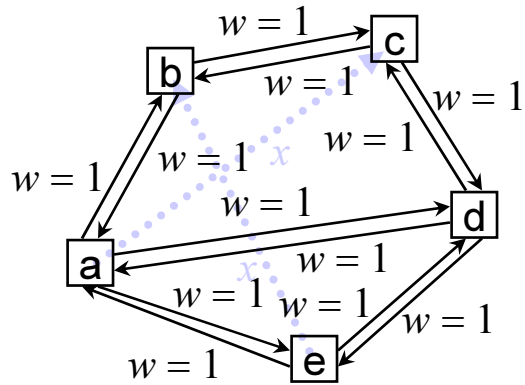
OSPF (2)

- Routers in OSPF networks typically apply **ECMP** (Equal Cost Multipath)
 - If there are multiple shortest paths from node n to node m , then node n tries to split the traffic uniformly to those outgoing links that belong to at least one of these shortest paths
 - However, this does **not** imply that the traffic load is distributed uniformly to all shortest paths! See the example on next slide.
- Traffic load distribution can be affected only **indirectly** by changing the link weights
 - splitting ratios ϕ_{pk} can not directly be changed
 - due to ECMP, the desired splitting ratios ϕ_{pk} may be out of reach

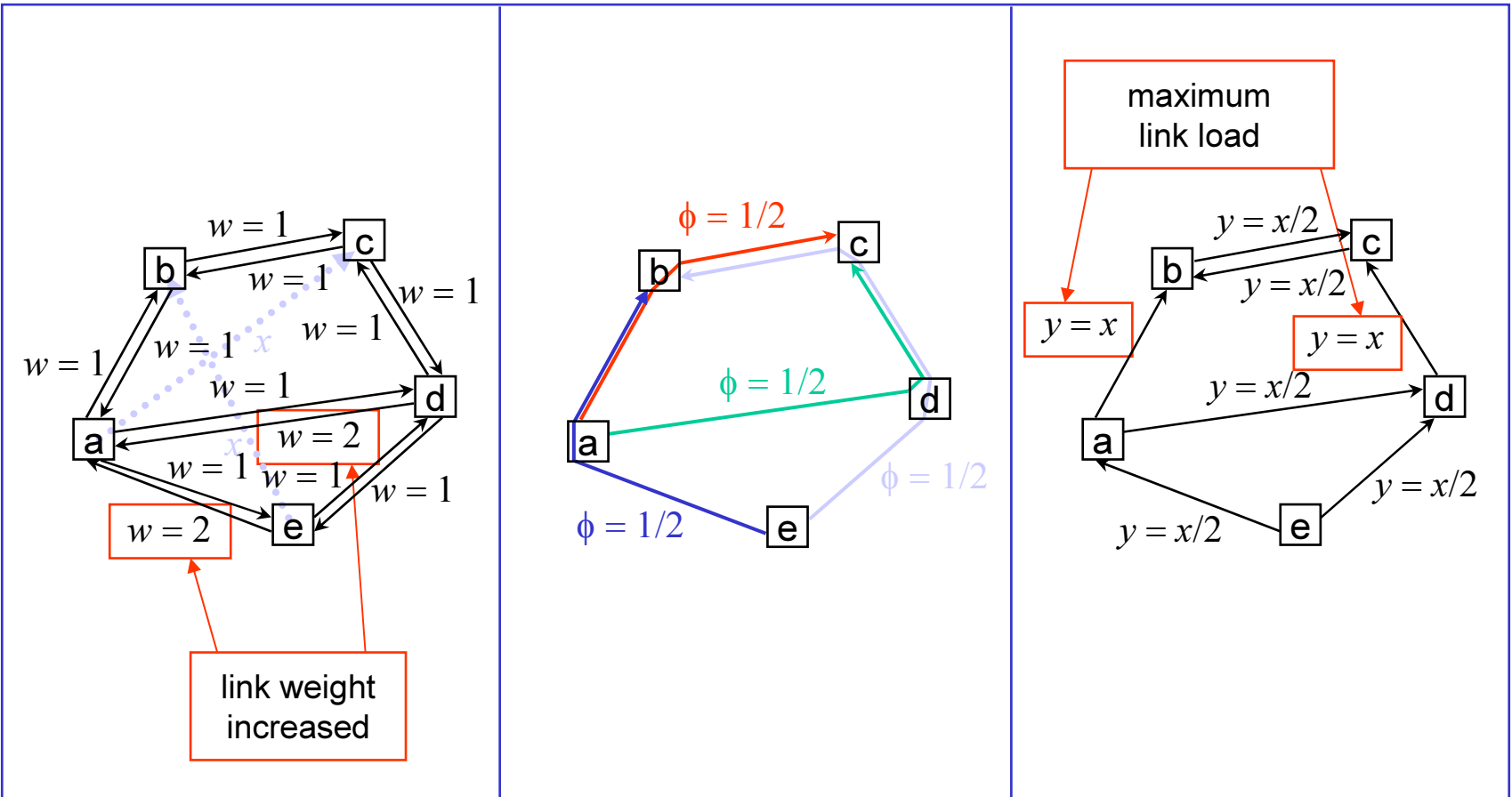
ECMP



Effect of link weights on load distribution (1)



Effect of link weights on load distribution (2)



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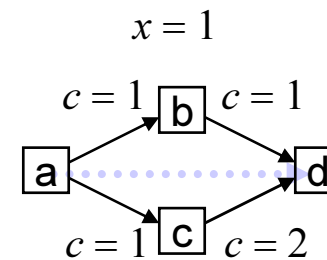
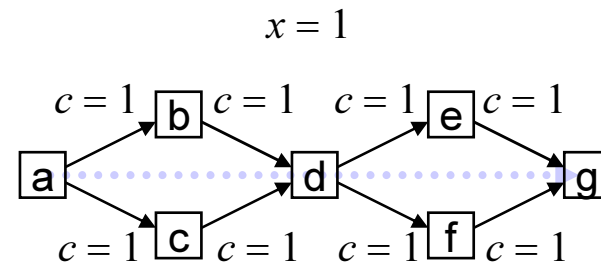
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Load balancing problem (1)

- Given a fixed topology and a traffic matrix, how to **optimally route** these traffic demands?
- One approach is to equalize the relative load of different links,

$$\rho_j = y_j / c_j$$

- Sometimes this can be done in multiple ways (upper figure)
- Sometimes it is not possible at all (lower figure)
- In this case, we may, however, try to get as close as possible, e.g. by minimizing the maximum relative link load (called: load balancing problem)



Load balancing problem (2)

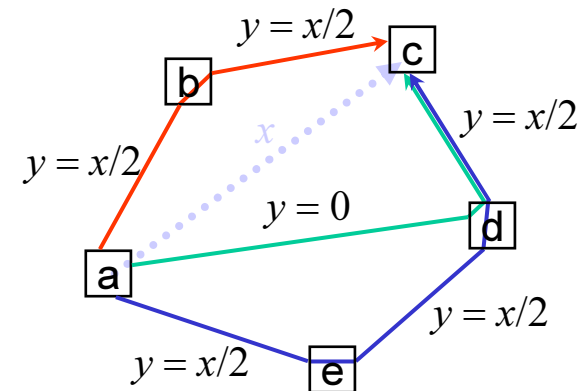
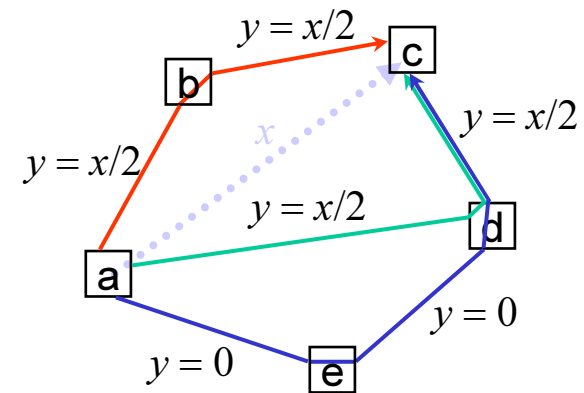
- **Load Balancing Problem:**

- Consider a network with topology (N, \mathcal{J}) , link capacities c_j , and traffic demands x_k . Determine the splitting ratios ϕ_{pk} so that the maximum relative link load is minimized

$$\begin{array}{l}
 \text{Minimize} \\
 \text{subject to}
 \end{array}
 \left\{ \begin{array}{l}
 \max_{j \in J} \frac{y_j}{c_j} \\
 y_j = \sum_{p \in P} \sum_{k \in K} A_{jp} \phi_{pk} x_k \quad \forall j \in J \\
 \sum_{p \in P} \phi_{pk} = 1 \quad \forall k \in K \\
 \phi_{pk} \geq 0 \quad \forall p \in P, k \in K
 \end{array} \right.$$

Load balancing problem (3)

- Load Balancing Problem has always a solution but this might not be unique
- Example:
 - the same maximum link load is achieved with routes of different length
 - the upper routes are better due to smaller capacity consumption
- A reasonable unique solution is achieved by associating a negligible cost with all the hops along the paths used

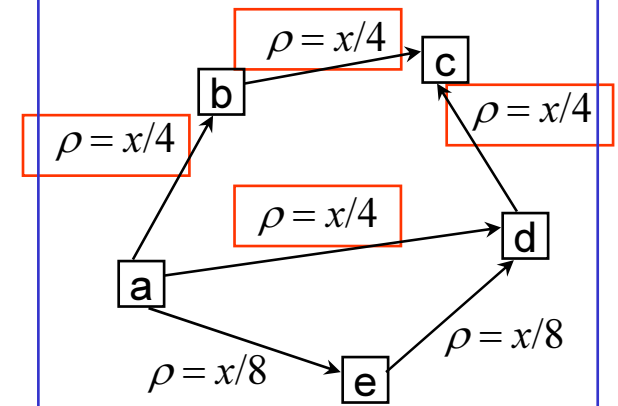
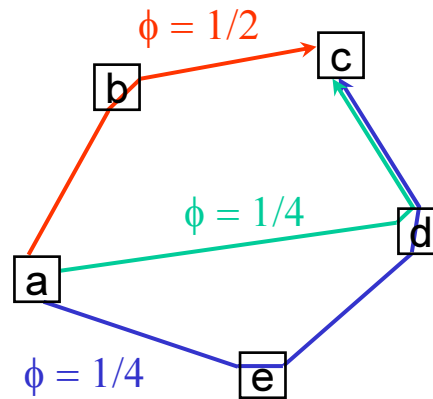
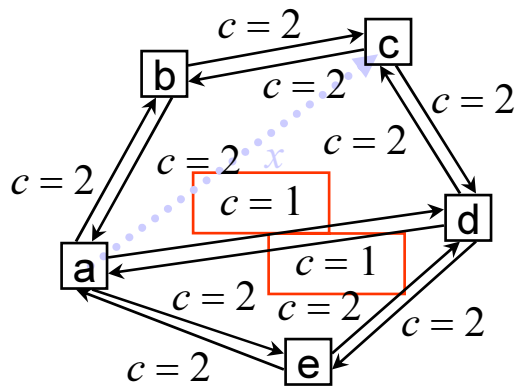


Load balancing problem (4)

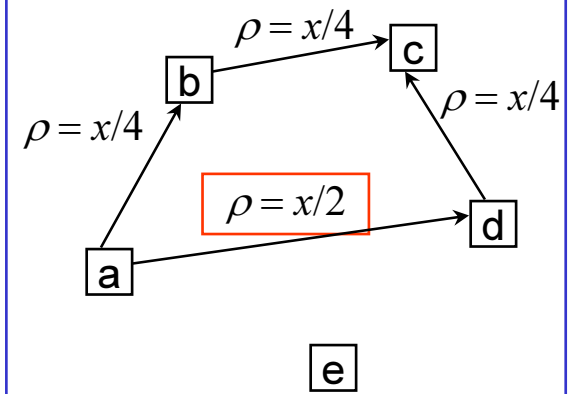
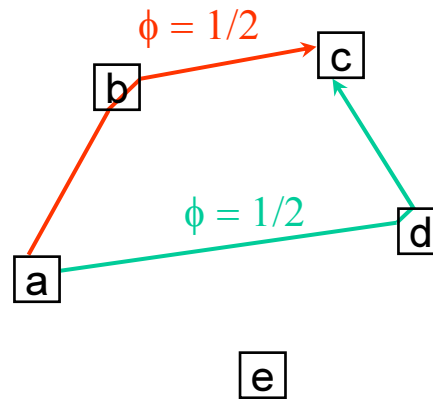
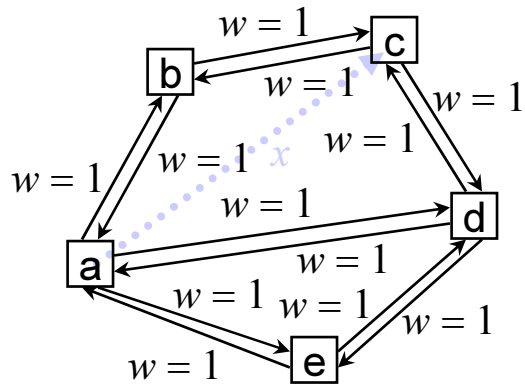
- **Load Balancing Problem** with a reasonable and unique solution:
 - Consider a network with topology (N, \mathcal{J}) , link capacities c_j , and traffic demands x_k . Determine the splitting ratios ϕ_{pk} so that the maximum relative link load is minimized with the smallest amount of required capacity

$$\begin{array}{l}
 \text{Minimize} \\
 \text{subject to}
 \end{array}
 \left\{ \begin{array}{l}
 \max_{j \in J} \frac{y_j}{c_j} + \varepsilon \sum_{j \in J} y_j \\
 y_j = \sum_{p \in P} \sum_{k \in K} A_{jp} \phi_{pk} x_k \quad \forall j \in J \\
 \sum_{p \in P} \phi_{pk} = 1 \quad \forall k \in K \\
 \phi_{pk} \geq 0 \quad \forall p \in P, k \in K
 \end{array} \right.$$

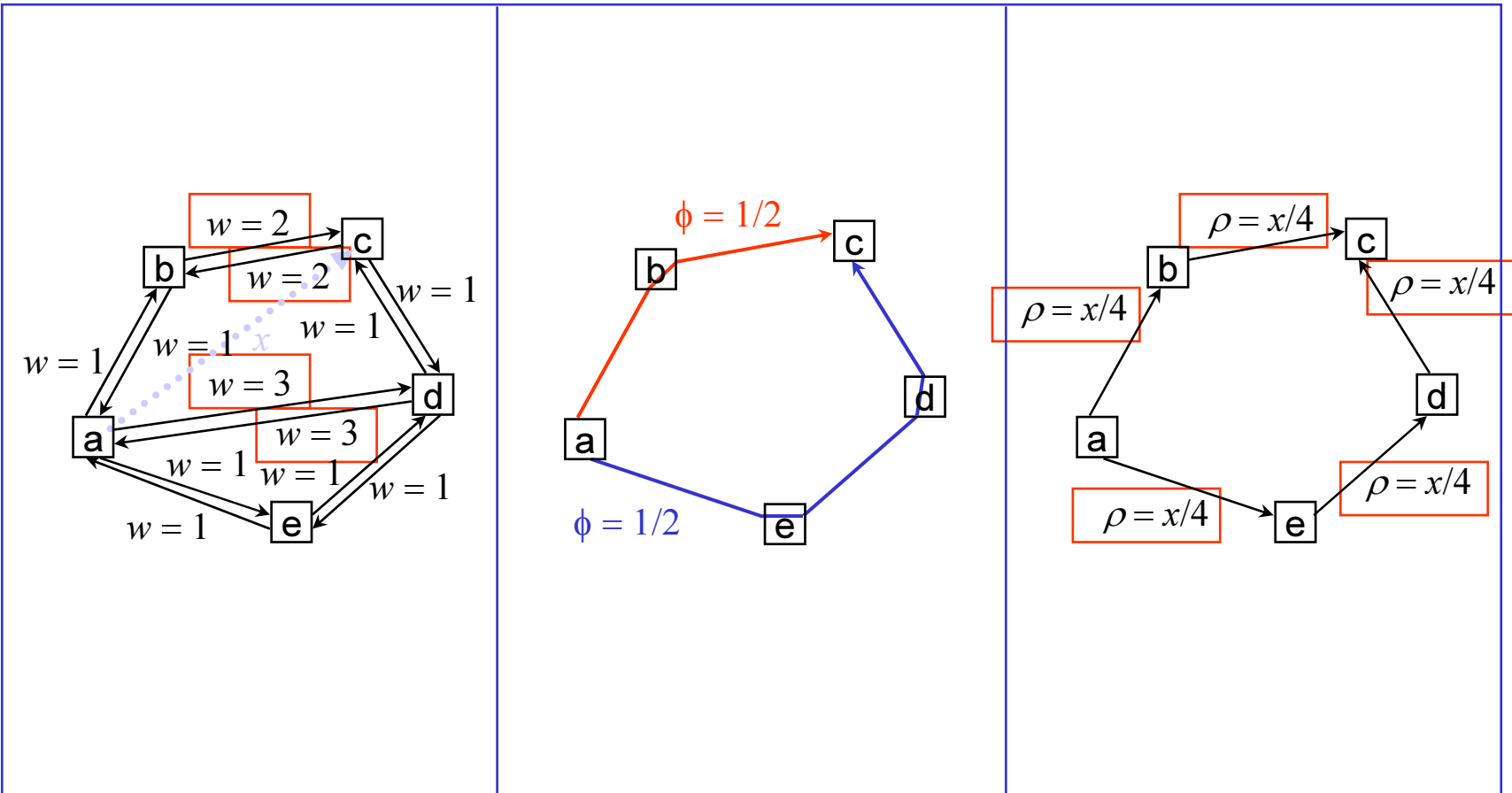
Example (1): optimal solution



Example (2): link weights $w = 1$



Example (3): optimal link weights



THE END

