Distance vector protocols

Distance Vector routing principles Routing loops and countermeasures to loops Bellman-Ford algorithm RIP, RIP-2

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Distance Vector Routing Principles

RIP – Routing Information Protocol is a basic protocol for interior routing

- RIP is a distance vector protocol
 - Based on the Bellman-Ford algorithm
- The routing table contains information about other known nodes
 - link (interface) identifier
 - distance (cost) in hops

E to	Link	Distance
E	-	0
В	4	1
A	4	2
D	6	1
С	5	1

- The nodes periodically send distance vectors based on the routing tables on all their links
- The nodes update their routing table with received distance vectors

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Let us study the principles of DV protocols

Example network with nodes A, B, C, D, E and links 1, 2, 3, 4, 5, 6.

A 1 B 2 C C D 6 E

Initial state: Nodes know their own addresses and interfaces, nothing more.

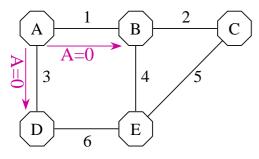
Node A creates its routing table:

From node A to	Link	Distance
A	- (local)	0

The corresponding distance vector (DV) is: A=0

Generation of routing tables starts when all routers send their DVs on all interfaces

Let's look at reception in Node B. First the table of B is:



From node B to	Link	Distance
В	-	0

- 1. B receives the distance vector A=0
- 2. B increments the DV with $+1 \Rightarrow A=1$
- 3. B looks for the result in its routing table, no match
- 4. B adds the result to its RT, the result is

From node B to	Link	Distance
В	-	0
A	1	1

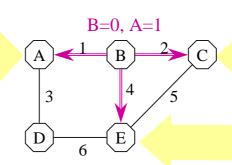
5. B generates its distance vector B=0, A=1

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B creates its own DV and sends it to all neighbors

A to	Link	Distance
A	-	0
В	1	1

$$A=2 > A=0$$

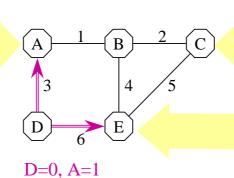


C to	Link	Distance
С	-	0
В	2	1
A	2	2

E to	Link	Distance
Е	-	0
В	4	1
A	4	2

D sends its distance vector to all neighbors

A to	Link	Distance
A	-	0
В	1	1
D	3	1



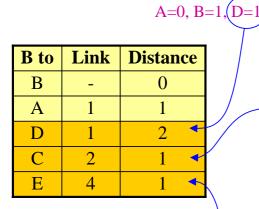
C to	Link	Distance
C	-	0
В	2	1
A	2	2

E to	Link	Distance
Е	-	0
В	4	1
A	4	2
D	6	1

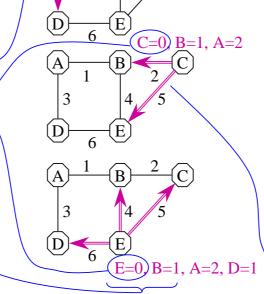
 $A=2 == A=2 \Rightarrow$ no change

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The nodes whose RT changed create DVs and send them to neighbors

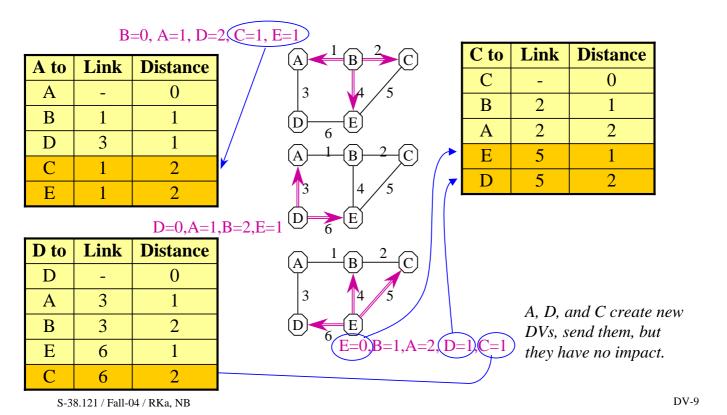


D to	Link	Distance
D	-	0
A	3	1
В	3	2
Е	6	1

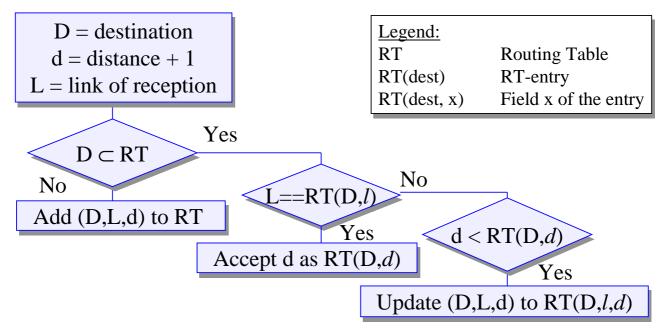


E to	Link	Distance
Е	-	0
В	4	1
A	4	2
D	6	1
С	5	1

Again the changes are sent ...



Processing of received distance vectors



Note: this is simplified, shows only the principle!

A link breaks...

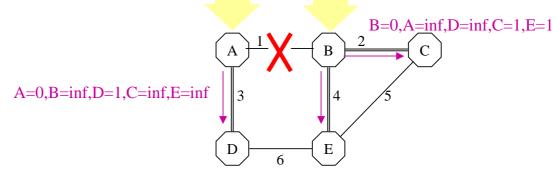
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A round of updates starts on link failure

A gives an infinite distance to the nodes reached through link 1

A to	Link	Distance
A	-	0
В	1	Inf.
D	3	1
С	1	Inf.
Е	1	Inf.

B to	Link	Distance
В	-	0
A	1	Inf.
D	1	Inf.
С	2	1
Е	4	1

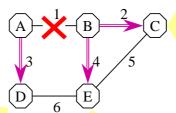


D, E and C update their routing tables

B=0,A=inf,D=inf,C=1,E=1

A=0,B=inf,D=1,C=inf,E=inf





C to	Link	Distance
С	-	0
В	2	1
A	2	Inf.
Е	5	1
D	5	2

A=1,B=inf,D=2,C=inf,E=inf

D to	Link	Distance
D	-	0
A	3	1
В	3	Inf.
Е	6	1
С	6	2

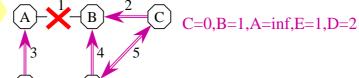
E to	Link	Distance
Е	ı	0
В	4	1
A	4	Inf.
D	6	1
С	5	1

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D, C, E generate their distance vectors...

A to	Link	Distance
A	-	0
В	1	Inf.
D	3	1
С	3	3
Е	3	2

B to	Link	Distance
В	-	0
A	1	Inf.
D	4	2
С	2	1
Е	4	1



D=0,A=1,B=inf,E=1,C=2 D E E=0,B=1,A=inf,D=1,C=1

D to	Link	Distance
D	-	0
A	3	1
В	6	2
Е	6	1
С	6	2

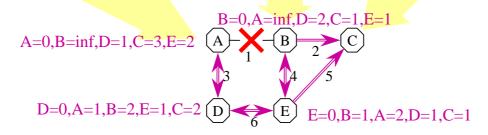
E to	Link	Distance
Е	ı	0
В	4	1
A	6	2
D	6	1
С	5	1

A, B, D, E generate their distance vectors

A to	Link	Distance
A	-	0
В	3	3
D	3	1
С	3	3
Е	3	2

B to	Link	Distance
В	-	0
A	4	3
D	4	2
С	2	1
Е	4	1

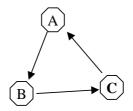
C to	Link	Distance
С	-	0
В	2	1
A	5	3
Е	5	1
D	5	2



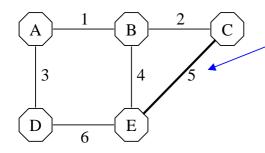
The result is that all nodes are able to communicate with all other nodes again.

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Routing loops



The DV-protocol may create a transient routing loop



Let's just look at the first link of each route.

Let's assume that cost of link 5 is 8. A stable initial state for routes to C would be:

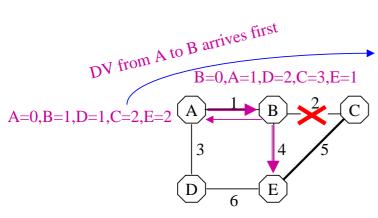
x to C	Link from x	Distance
A→C	1	2
$B \rightarrow C$	2	1
C→C	-	0
D→C	3	3
$E \rightarrow C$	4	2

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transient - hetkellinen, ohimenevä, väliaikainen

DV-17

Link 2 fails



All packets to C are sent to B. B sends them to A. A sends them back to B... until TTL=0. (Bouncing effect)

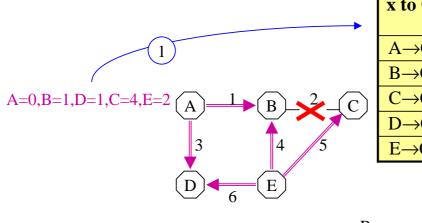
x to C	Link from x	Distance
$A \rightarrow C$	1	2
$B \rightarrow C$	2	Inf.
$C \rightarrow C$	-	0
D→C	3	3
E→C	4	2

x to C	Link from x	Distance
$A \rightarrow C$	1	4
В→С	1	3
$C \rightarrow C$	-	0
D→C	3	3
$E \rightarrow C$	4	4

Intermediate state

DV-18

A and E send their distance vectors



x to C	Link from x	Distance
$A \rightarrow C$	1	4
$B \rightarrow C$	1	5
$C \rightarrow C$	-	0
D→C	3	5
$E \rightarrow C$	4	4

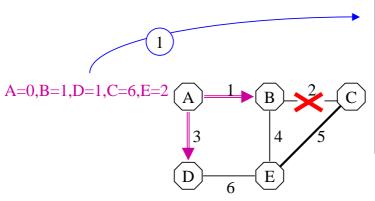
B generates a new DV: B=0,A=1,D=2,C=5,E=1

⇒ Distance seen by A to C grows to 6

Distance vectors sent by C do not change anything because of high link cost DV-19

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A sends a new distance vector

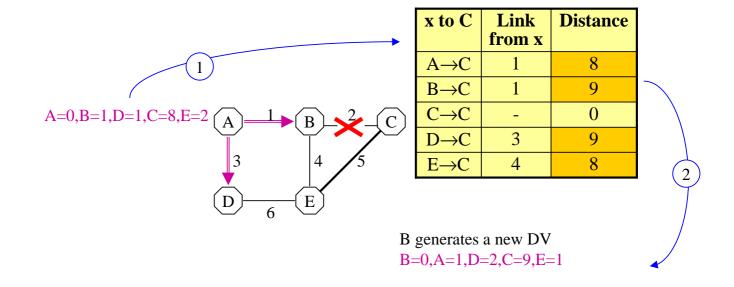


x to C	Link from x	Distance
$A \rightarrow C$	1	6
$B \rightarrow C$	1	7
$C \rightarrow C$	-	0
D→C	3	7
E→C	4	6

B generates a new DV B=0,A=1,D=2,C=7,E=1

 \Rightarrow Distance seen by A to C grows to 8

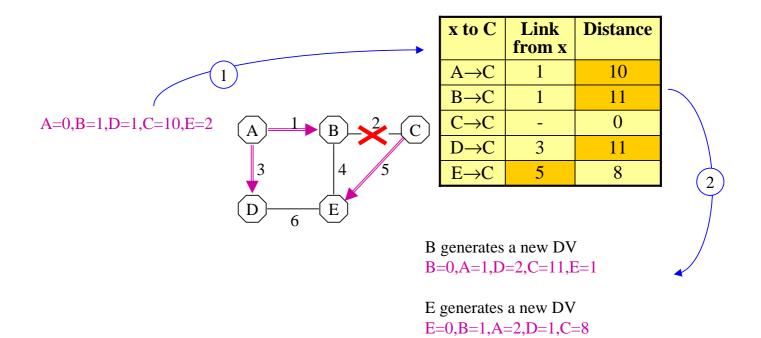
A sends a new distance vector



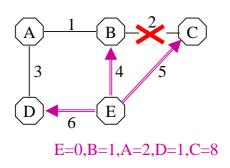
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 \Rightarrow Distance seen by A to C grows to 10

A sends a new distance vector



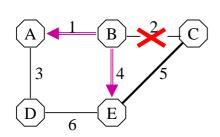
E sends a new distance vector



x to C	Link from x	Distance
$A \rightarrow C$	1	10
$B \rightarrow C$	4	9
$C \rightarrow C$	-	0
D→C	6	9
$E \rightarrow C$	5	8

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B send its DV but the tables are already OK



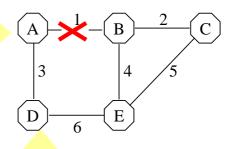
x to C	Link from x	Distance
$A \rightarrow C$	1	10
$B \rightarrow C$	4	9
$C \rightarrow C$	-	0
D→C	6	9
$E \rightarrow C$	5	8

- Each update round increased the costs by 2
- The process progresses in a random order, because it is genuinely parallel in nature.
- During the process, the state of the network is bad. DV-packets may be lost due to the overload created by bouncing user messages

Counting to infinity occurs when failures break the network to isolated islands (1)

- Link 1 is broken, and the network has recovered.
- All link costs = 1

A to	Link	Distance
D	3	1
A	-	0
В	3	3
Е	3	2
С	3	3



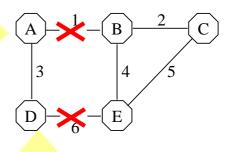
D to	Link	Distance
D	-	0
A	3	1
В	6	2
Е	6	1
С	6	2

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Counting to infinity occurs when failures break the network to isolated islands (2)

- Also link 6 breaks.
- D updates its routing table but has not yet sent its distance vector.

A to	Link	Distance
D	3	1
A	-	0
В	3	3
Е	3	2
С	3	3



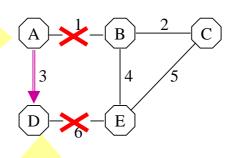
D to	Link	Distance
D	-	0
A	3	1
В	6	Inf.
Е	6	Inf.
С	6	Inf.

Counting to infinity occurs when failures break the network to isolated islands (3)

 A sends its distance vector first:

 D adds the information sent by A into its routing table.

A to	Link	Distance
D	3	1
A	-	0
В	3	3
Е	3	2
С	3	3



D to	Link	Distance
D	ı	0
A	3	1
В	3	4
Е	3	3
С	3	4

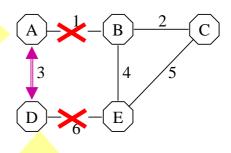
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Counting to infinity occurs when failures break the network to isolated islands (4)

 The result is a loop. Costs are incremented by 2 on each round.

A to	Link	Distance
D	3	1
A	-	0
В	3	5
Е	3	4
С	3	5

 We need to define infinity as a cost greater than any normal route cost.



D to	Link	Distance
D	1	0
A	3	1
В	3	4
Е	3	3
С	3	4

The first method to avoid loops is to send less information

The split horizon rule:

If node A sends to node X through node B, it does not make sense for B to try to reach X through A

 \Rightarrow A should not advertise to B its short distance to X

Implementation choices:

- 1. Split horizon
 - A does not advertise its distance to X towards B at all
 - ⇒ the loop of previous example can not occur
- 2. Split horizon with poisonous reverse
 - A advertises to B: X=inf.
 - ⇒ two node loops are killed immediately

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Split horizon example

A to	Link	Distance	Δ
D	3	1	
A	-	0	3
В	3	2	
С	3	3	$ \qquad \qquad (B) - (C) $

- Normally:
 - A sends: A=0,B=2,C=3,D=1
- Split horizon:
 - A sends: A=0
- Split horizon with poisonous reverse:
 - A sends: A=0,B=inf,C=inf,D=inf

Split horizon example

A to	Link	Distance	
В	3	1	
A	-	0	3
D	3	2	
С	1	1	$\left(\begin{array}{c} B \\ \hline \end{array} \right)$

- Normally:
 - A sends: A=0,B=1,C=1,D=2

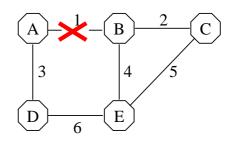
• Split horizon:

- A sends: A=0,C=1
- Split horizon with poisonous reverse:
 - A sends: A=0,B=inf,C=1,D=inf,

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Three-node loops are still possible (1)

- Link 1 is broken, and the network has recovered.
- All link costs = 1



Note that A sends

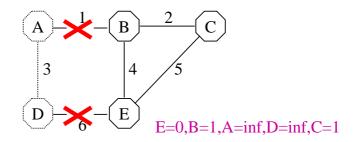
different DVs on link 1

x to D	Link from x	Distance
$B \rightarrow D$	4	2
C→D	5	2
E→D	6	1

Three-node loops are still possible (2)

- Also link 6 fails.
- E sends its distance vector to B and C

E=0,B=1,A=inf,D=inf,C=1

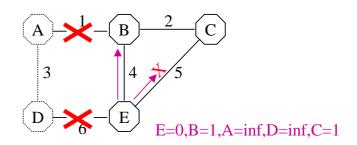


x to D	Link from x	Distance
$B \rightarrow D$	4	2
C→D	5	2
E→D	6	Inf.

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Three-node loops are still possible (3)

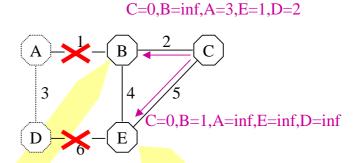
- Also link 6 fails.
- E sends its distance vector to B and C
 E=0,B=1,A=inf,D=inf,C=1
- ... But the DV sent to C is lost



x to D	Link from x	Distance
$B \rightarrow D$	4	Inf.
C→D	5	2
E→D	6	Inf.

Three-node loops are still possible (4)

Now C sends its poisoned DV



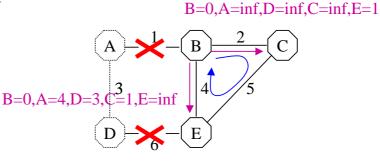
B to	Link	Distance
В	-	0
A	2	4
D	2	3
С	2	1
Е	4	1

E to	Link	Distance
В	4	1
A	6	Inf.
D	6	Inf.
С	5	1
Е	ı	0

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Three-node loops are still possible (5)

- B generates its poisoned distance vectors
- The three node loop is ready
- On link 5 cost=4 is advertised. C's knowledge about the distance to D grows ...
- Routes to D do not change except that the costs keep growing, nodes count to infinity. This finally breaks the loop.



x to D	Link from x	Distance
$B \rightarrow D$	2	3
C→D	5	2
$E \rightarrow D$	4	4

When should a DV-protocol advertise?

Time of advertisement is a compromise:

- immediate delivery of change info
- recovery from packet loss
- need to monitor the neighbors
- sending all changes at the same time
- traffic load created by the protocol
- = Faster
- = Slower

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The second method to avoid loops is to use triggered updates

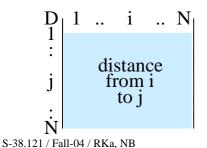
- Entries in the routing tables have refresh and obsolescence timeouts.
- RIP advertises
 - when the refresh timer expires, and
 - when a change occurs in an entry (=triggered update).
- Triggered updates reduce the probability of loops
- Loops are still possible, e.g. because of packet loss
- Triggered updates speed up counting to infinity

The Bellman-Ford algorithm

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Bellman-Ford algorithm (1)

- DV-protocols are based on the Bellman-Ford algorithm
- Centralized version:
 - Let *N* be the number of nodes and *M* the number of links.
 - L is the link table with M rows, L[l].m link cost link source L[l].d link destination
 - D is $N \times N$ matrix, such that D[i,j] is the distance from i to j
 - H on $N \times N$ matrix, such that H[i,j] is the link that i uses to send to j



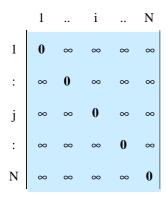
Both directions are presented separately in the link table!

A column \equiv DV of the corresponding node

DV-40

Bellman-Ford algorithm (2)

• Initialized distance and link matrices



Distance matrix D

	1		i		N
1	-1	-1	-1	-1	-1
:	-1	-1	-1 -1	-1	-1
j	-1	-1	-1	-1	-1
:	-1	-1	-1	-1	-1
N	-1	-1	-1 -1	-1	-1

Link matrix H

From i to j

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Bellman-Ford algorithm (3)

1. Initialization: (previous slide)

If i=j, then D[i,j] = 0, else $D[i,j] = \inf$.

Initialize \forall H[i,j] = -1.

- 2. \forall links l and \forall destinations k:
 - i. set i = L[l].s, j = L[l].d
 - ii. calculate d = L[l].m + D[j,k]
 - iii. if d < D[i,k], set D[i,k] = d; H[i,k] = l.
- 4. If at least one D[i,k] changed, go to step 2, else stop.

Bellman-Ford algorithm (4)

- First in D-matrix appear one hop link distances, then two hop link distances, etc.
- Number of steps $\leq N$
- Complexity: $O(M \cdot N^2)$
- Complexity of the distributed version: $O(M \cdot N)$

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RIP protocol

RIP-protocol properties (1)

- Simple protocol. Used before standardization.
- RIP version 1
 - RFC 1058 in 1988
- RIP is used inside an autonomous system
- RIP works both on shared media (Ethernet) and in point-to-point networks.
- RIP runs on top of UDP (port 520) or IP.

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RIP-protocol properties (2)

• An entry in the routing table represents a network, a subnetwork or a host:

- <netid,0,0> represents a network

- <netid,subnetid,0> represents a sub-network

- <netid,subnetid,host> represents a host (used only in exceptional cases)

- <0.0.0> represents a route out from the autonomous system

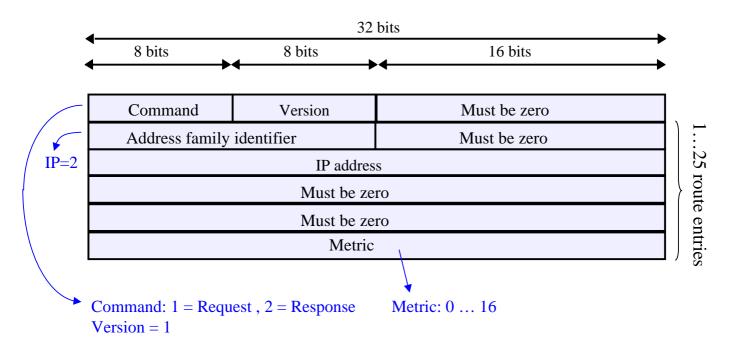
- The mask must be manually configured.
- Sub-network entries are aggregated to a network entry on interfaces belonging to another network.

RIP-protocol properties (3)

- Distance = hop count = number of links on a path (route).
 - No other metrics
- Distance 16 = infinite.
- RIP advertises once in 30s.
 - If an entry is 180s old \Rightarrow distance is set to infinite
 - Advertisements must be randomized to avoid bursts of RIP updates. 1-5 s.
- RIP also sends 1-5 s after an update (triggered updates).
- RIP uses poisoned vectors.

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RIP message format



RIP routing table

A routing table entry contains

- Destination IP address
- Distance to destination
- Next hop IP address
- "Recently updated" flag
- Several timers (refresh, obsolescence...)

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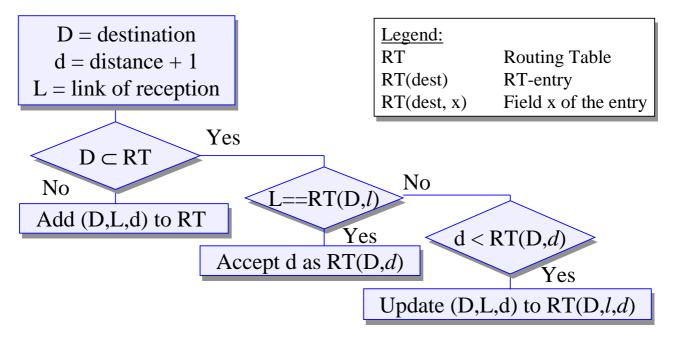
Routing table example

• Example Kernel routing table

netstat -nr

Kernel routing table							
Destination	Gateway	Genmask	Flags	Metric	Ref	Use	Iface
127.0.0.1	*	255.255.255.255	UH	1	0	2130	100
191.72.1.0	*	255.255.255.0	U	1	0	3070	eth0
191.72.2.0	191.72.1.1	255.255.255.0	UG	1	0	1236	eth0
191.72.3.0	191.72.1.2	255.255.255.0	UG	1	0	3212	eth0

Processing of Received Distance Vectors



Note: this is simplified, shows only the principle!

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RIP response messages

- Distance vectors are sent in response messages
- Periodic updates (30 seconds period)
 - All routing table entries
 - Different DV on different links because of poisoned vectors
 - More than 25 entries ⇒ several messages
- Triggered updates after changes
 - Contains changed entries
 - 1-5 seconds delay, so that the message contains all updates that are related to the same change
- Destinations with infinite distance can be omitted if the next hop is same as before.

RIP request messages

- The router can request routing tables from its neighbors at startup
 - Complete list
 - Response similar to normal update (+ poisoned vectors)
- Partial routing table
 - For debugging
 - No poisoned vectors

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Silent nodes

- When only RIP was used, hosts could listen to routing traffic and maintain their own routing tables
 - Which router is closest to the destination?
 - Which link, if several available?
- These where "silent nodes", that only listened to routing traffic without sending
- Nowadays there are too many routing protocols
 - RIP-2, OSPF, IGRP, ...

Historical

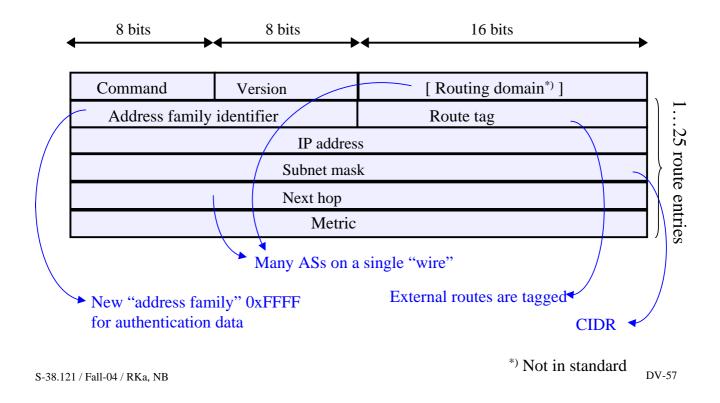
RIP version 2

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RIP version 2

- RFC-1388 (1387,1389)
- Why?
 - Simple and lightweight alternative to OSPF and IS-IS
- RIP-2 is an update that is partially interoperable with RIP-1
 - A RIP-1 router understands some of what a RIP-2 router is saying.
- Improvements
 - Authentication
 - Support for CIDR
 - Next hop -field
 - Subnet mask
 - External routes
 - Updates with multicast

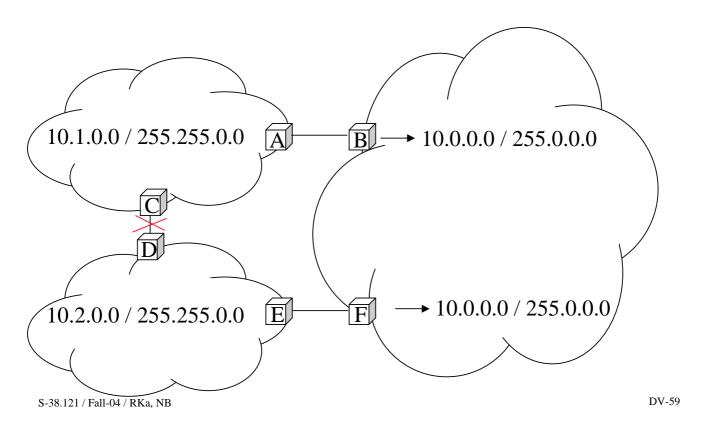
RIP version 2 – messages



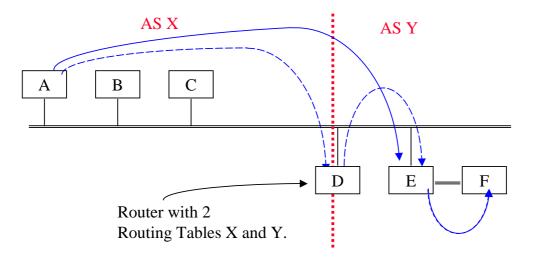
Routing from one sub-net to another (1)

- In RIP-1 the subnet mask is not known outside the subnet, only network-id is sent in an advertisement out from a subnet
 - ⇒ A host and a subnet can not be distinguished
 - ⇒ All subnets must be interconnected with all other subnets and exterior traffic is received in the nearest router independent of the final destination inside our network
- RIP-2 corrects the situation by advertising both the subnet and the subnet mask
 - Masks of different length within a network
 - CIDR
 - RIP-1 does not understand

Routing from one sub-net to another (2)



Routing domain and next hop



Next hop \Rightarrow D advertises in X: the distance to F is f and the next hop is E!

Support for local multicast

- RIP-1 broadcasts advertisements to all addresses on the wire
 - Hosts must examine all broadcast packets
- RIP-2 uses a multicast address for advertisements
 - -244.0.0.9
 - No real multicast support needed, since packets are only sent on the local network
- Compatibility problems between RIP-1 and RIP-2

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Observations about RIP (1)

- Routers have a spontaneous tendency to synchronize their send times. This increases the probability of losses in the net. Therefore, send instants are randomized between 15s ... 45s.
- Reason: send interval = constant + time of message packing + processing time of messages that are in the queue.

Observations about RIP (2)

- When RIP is used on ISDN links a new call is established per 30s
 - \Rightarrow Expensive.
- Slow network \Rightarrow queue length are restricted.
 - RIP sends its DVs 25 entries/message in a row ⇒ RIP messages may be lost.
- A correction proposal: ack all DVs: no periodic updates
 - ⇒ If there are no RIP message: assume that neighbor is alive and reachable
 - \Rightarrow Info on all alternative routes is stored.